

Non-abelian $D\emptyset$ -branes in curved backgrounds : from Matrix diffeomorphisms to a Geometric Myers Effect

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- Introduction
- $D\emptyset$ -branes and diffeomorphisms
- Matrix diffeomorphisms from Open Strings
- A non-abelian DBI action
- Evidence for a geometric Myers effect
- Outlook & Conclusion

Stringy Geometry

- In String Theory, Geometry is defined by probes.

- "Geometry" is not universal!
 - Closed vs. Open Strings vs. D-branes
 - Open with $B_{NS} \neq 0$
yields noncommutative geometry
 - Open with $F_{RR}^L \neq 0$
gives rise to the Myers effect
 - D-brane geometry, is well-defined.
i.e. $D\phi$ -metric is not renormalized.
- Douglas

D -branes in Curved Space

- Question:

What is the geometry of N coincident D -branes?

- Single D -brane effective action:
Particle in Curved Space

$$S = \int e^{-\varphi} \sqrt{|G_{ij} \partial_a x^i \partial_b x^j + F_{ab}|}$$

- N coincident D -branes in flat space

$$x^i \in \mathbb{R} \sim U(1) \rightarrow X^i \in U(N)$$

$$S = \int \frac{1}{2} \text{Tr} \partial_a X^i \partial^a X_i + \frac{F^2}{4} - [X^i, X^j]^2$$

- N coincident D -branes in curved space

$$S = \int \text{tr } G_{ij}(X) \partial X^i \partial X^j$$

to determine
this!

Matrix valued diffeomorphisms

- What is the action of N coincident D-branes in curved space?

- One expects

$$S = -m \int \mathrm{tr} \sqrt{G_{ij}(x) \dot{X}^i \dot{X}^j} + \dots$$

- Ordering?

Lore

$$[X^i, X^j] \neq 0$$

- Additional interactions?
(viz. potential)

YES

- Characteristic of curved space:

Invariance under diffeomorphisms

- Recall

$$S_{\text{part}} = \int \sqrt{g_{ij}(x) \dot{x}^i \dot{x}^j}$$

$$\delta S_{\text{part}} = 0 ; \quad \delta x^i = \xi^i(x) ; \quad \delta g_{ij} = -D_i \xi_j$$

- Graviton is gauge field of diff.
Coupling is unique

- Search for a symmetry principle:
Matrix Diffeomorphisms

Overview

- What: the action for D \emptyset branes in curved space
- How: by requiring diffeomorphism invariance **PLUS** ... string thy

- Other approaches

- Susy and off-diagonal fluctuations and geodesics

Douglas Kato
Ooguri

- Susy and kappa symmetry

Bergshoeff, de Roo
Sevrin

- (Linear) couplings from Matrix theory

Taylor vRaamsdonk
Okawa Ooguri

- Coset-like approaches from dN^2 -sigma models

Chamseddine

:

- Why:
 - Probes of Quantum Geometry (Myers)
 - Connection between D \emptyset -brane Mechanics and Matrix theory
 - Matrix Models :

- $O(N)$ vector models
- LG models
- Random Matrix Theory

Diff invariant version
of N-particle QM.

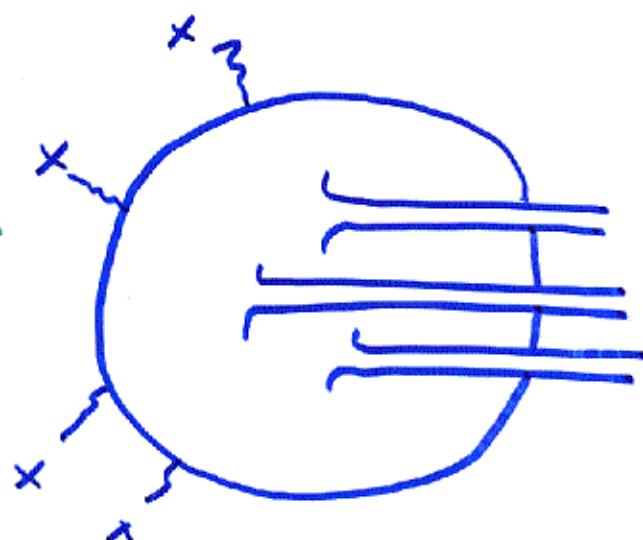
Intermezzo: NC Geometry in String Theory

- STANDARD non-commutative Geometry

$$[x^i, x^j] = i\theta^{ij}$$

$$\delta_{ik} \delta_{lj} = 0$$


 Open strings
 Associative
 \star -product



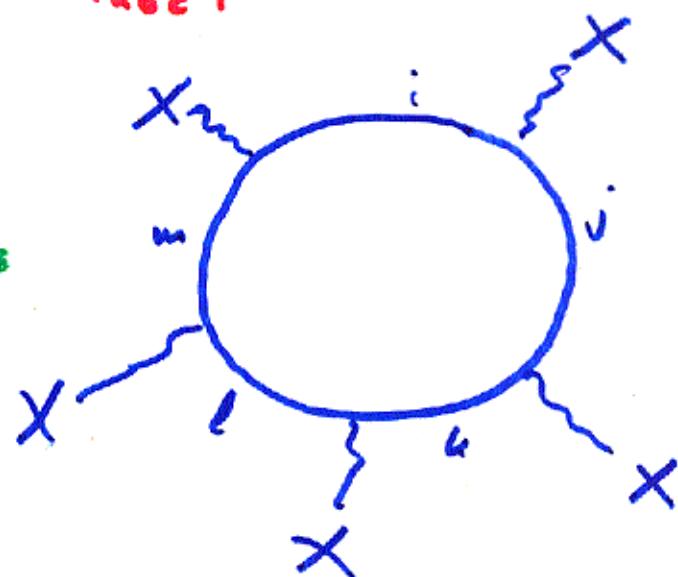
Connes
 Seiberg Witten
 Kontsevich
 Cattaneo Felder
 Connes Douglas Hull

- D-brane non-commutative Geometry

$$[x^i, x^j] = x^m x^n f_{abc} T^c$$


 Open Strings

$\tilde{\star}$ -product?



Witten

Contents

- Exact Formulation of the problems

- Matrix DIFFeomorphisms
- Representations and linear couplings

- An action by way of open strings

- Characteristics of amplitudes
- Normal Coordinates and diffeomorphisms
- Matrix Geometry
- An action

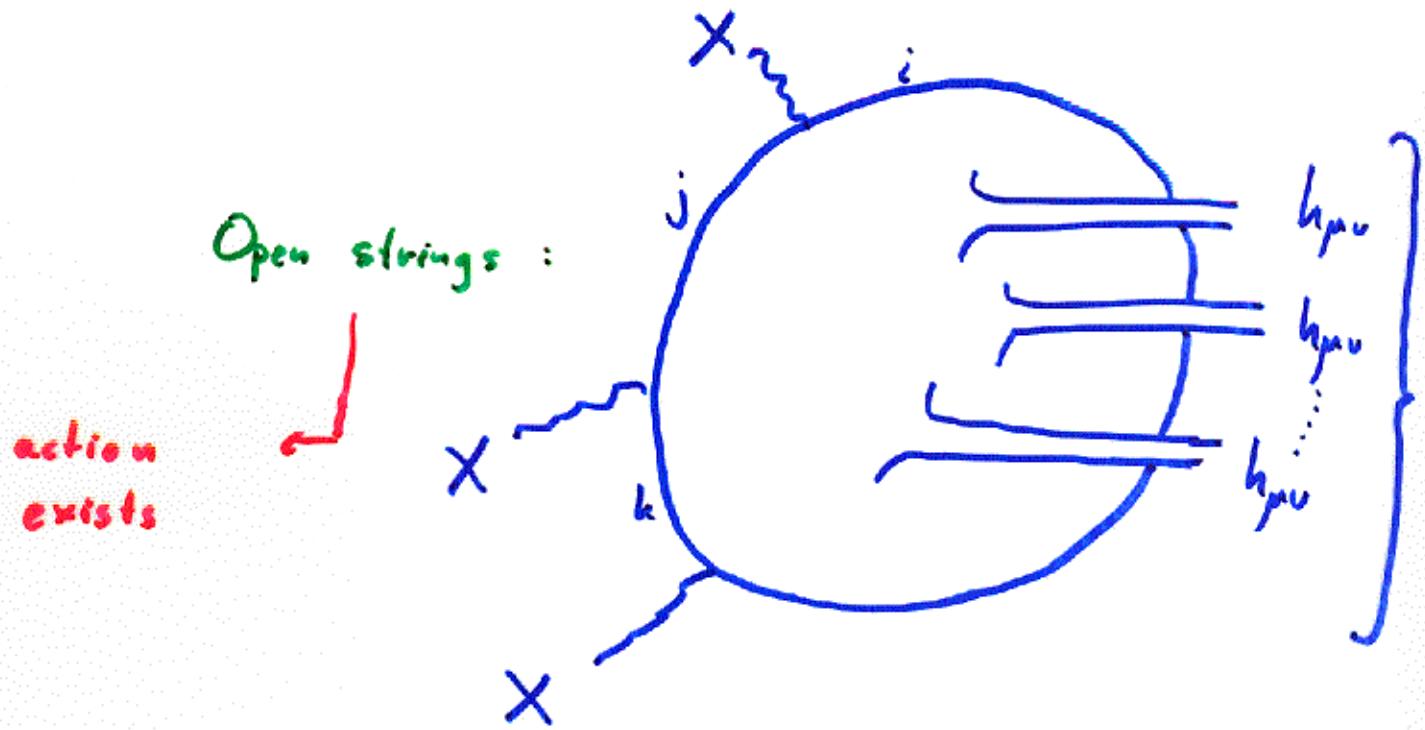
- Properties

- Potential / T-duality
- D-geometry constraints

- Consequences

[-] Geometric Myers effect ?

- $D\emptyset$ -branes coupled to gravity



Exact formulation

- Given the action

$$\begin{aligned}
 S[g, x] &= \int \text{tr } G_{ij}(x) \dot{x}^i \dot{x}^j \\
 &\equiv \int \text{tr} (\dot{x}^i \dot{x}^j x^{k_1} \dots x^{k_n}) \frac{\partial^n}{n!} g_{ij}(0)
 \end{aligned}$$

↗ infinite #
couplings

Find the precise orderings/couplings such that

D
i
g
e
o
m
e
t
r
y

- the action has a single trace Tseytlin
- If $x^i = \text{diag}(x_1^i, \dots, x_N^i)$ the reduces to a sum of N particle actions
- Off-diagonal fluctuations have masses proportional to $d(x_1, x_N)$ Douglas
- Classical Moduli space is the symmetric product M^N / S_N
- the action is invariant under $x \xrightarrow{?} x'(x)$ for $g \rightarrow g'$ NEW
- Linear couplings agree with known results (Taylor vR ; Ochiai Ooguri) NEW

Linearized Coupling and Linearized diffeomorphisms

- Single D-brane (particle)

$$\begin{aligned}
 S &= \int d\tau g_{ij}(x) \dot{x}^i \dot{x}^j = \int d\tau \dot{x}^i \dot{x}^j (\eta_{ij} + h_{ij}(x)) \\
 &\equiv \int d\tau \dot{x}^i \dot{x}_i + T^{ij}(x) h_{ij}(x) \\
 &\quad \begin{array}{l} \nearrow \\ T^{ijk_1 \dots k_n} \end{array} \quad \begin{array}{l} \nearrow \\ \frac{\partial^n}{n!} h_{ij} \Big|_{x=0} \end{array} \\
 &\quad \text{couplings}
 \end{aligned}$$

- Current (stress-tensor) $T^{ij}(x)$ conserved
(on shell)
"follows" from invariance under infinitesimal diffs:

$$\delta x^i = \xi^i(x) \quad ; \quad \delta h_{ij} = -D_i(h)\xi_j - D_j(h)\xi_i$$

Linearized diffs II:

- To first order in ϵ , the action

$$S = \int d\tau \dot{x}^i \dot{x}_i + T^{ij}(x) h_{ij}(x)$$

is also invariant under linear diffs.

$$h_{ij} \sim \epsilon \quad ; \quad \xi^i \sim \epsilon$$

\uparrow
coupling constant

$$\begin{aligned} S x^i &= \xi^i(x) \\ &= x^{k_1} \dots x^{k_n} \frac{\partial^n \xi^i}{n!} \Big|_{x=0} \end{aligned}$$

$$\Rightarrow \delta h_{ij} = -\partial_i \xi_j - \partial_j \xi_i + O(\epsilon)$$

$$\Rightarrow \delta \partial^n h_{ij} = -\partial^n \partial_i \xi_j + O(\epsilon)$$

- "Reconstruction": to first order the gauge field coupling to a conserved current yields an invariant action iff

$$\delta A_i = -\partial_i \epsilon$$

Linearized Coupling and Linearized diff. III

- Linear coupling to graviton (stress-tensor); known from Matrix theory and string amplitudes

(Taylor vR; Ozaka Ooguri)

$$S = \int d\tau \dot{x}^i \dot{x}_i + T^{ij(k_1 \dots k_n)} \frac{\partial^{(n)}}{n!} h_{ij} + \dots$$

$$T^{ij(k_1 \dots k_n)} = \text{Str}(\dot{x}^i \dot{x}^j x^{k_1} \dots x^{k_n})$$

Tseytlin

DIFFERENT FOR BOSONIC STRING

- Stress tensor is conserved (on shell) \Leftrightarrow
Invariant under linearized diffeomorphisms

$$\delta h_{ij} = -\partial_i \xi_j - \partial_j \xi_i + \dots$$

$$\delta x^i = \xi^i(x) \equiv \text{Sym}(x^{k_1} \dots x^{k_n}) \frac{\partial^n}{n!} \xi^{(0)}$$

- "Reconstruction" of higher order terms ...

Structure of Matrix diffeomorphisms

- derive by Noether method

- Very difficult!
- Need to guess 2nd order

$$\begin{aligned}\delta^{(2)} X &\sim \partial h \oint [X, X], X \\ S^{(2)} &\sim h^2 [X, \dot{X}]^2\end{aligned}$$

- "Normally" need either $\delta^{(2)} X$ or $S^{(2)}$
- Important to note that

$$S X = \oint [g, X]$$

↑ gauge field

- Group DIFF of matrix-valued diffs.

- Lift diff to DIFF

Group Structure

$$\begin{array}{ll} \text{diff} & x''(x'(x)) = x''(x) \\ \in \text{DIFF} & x''(x'(x)) = U x''(x) U^+ \end{array} ?$$

- HAS NO SOLUTION

- $\{g, X\}$ form a representation

Intermezzo

- To implement Matrix-valued diffeomorphisms:

- Seek an action that obeys

$$S[x, g] = S[x'(g, x), g'(g)]$$

- Extremely nonlinear problem

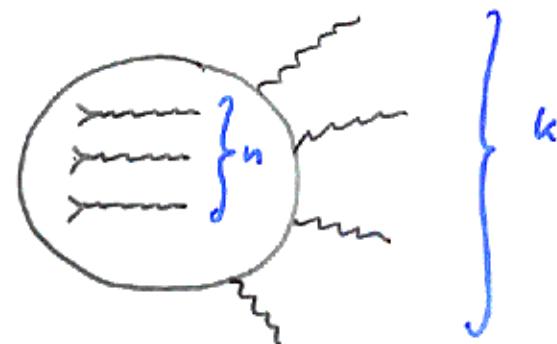
- Brute force (Noether) "fails"

- Can we find some extra information?

D-brane actions from open strings

- D-brane effective action = effective action reconstructed from open string amplitudes.

- Disc amplitudes with k open-string vertices and n graviton vertices



- Diffeomorphism invariance of string theory
→ diff invariance of the effective action
- $n=1$ graviton amplitudes yield linearized result
- Rather than compute amplitudes, try to glean information from the general structure

String Effective Actions Intermezzo

- Why not use β -functions?

- β -functions work for massless fields (marginal operators) in a BG-field method
- the matrix X corresponds to the open-string field V with vertex $V_i(k) \partial_n Y^i e^{ikY}$
- Hence we would need "to turn-on" off-diagonal parts of X , but these correspond to massive operators

- Does the LEEA in fact exist?

- Does the matrix structure survive $\alpha' \rightarrow 0$
- Physical expectation YES
- Provided, masses $\frac{\langle X \rangle}{R} \ll \sqrt{\alpha'}$
- Inspection of two-graviton amplitudes suggests a consistent $\alpha' \rightarrow 0$ limit exists

Lessons from open strings

- The action from amplitudes

Dirichlet
↓
 $y(0) = y(\pi)$

- Vertices = fluctuations around x, η_{ij}

$$V_i(h) \partial_n Y^i e^{ikY} ; h_{ij}(u) \partial Y^i \partial Y^j e^{ikY}$$

- Action

$$S = S [h_{ij}(x), \tilde{X}^i]_{\eta, x}$$

$$\tilde{X}^i = (\eta + h)^{ij} V_j$$

- Can we relate this to $S[g, X]$?

- Vertex $V_i(k=0) \Rightarrow$ shift in x !

- V_i transform as vectors

matrices 

caution: contact terms

$$\tilde{X}^i \sim \Delta X^i$$

⇒ Can we preserve the vector transformation properties?

Normal Coordinates

- Particle

- Final action depends on

$$X = \bar{x} + \tilde{X} + \mathcal{O}(\tilde{X}^2)$$

- X should transform as a vector
 \Leftrightarrow expansion is known: covariant non-linear BG-field expansion

$$x = \bar{x} + \tilde{x}^i - \sum \Gamma^i_{h_1 h_2 \dots h_n} \tilde{x}^{h_1} \dots \tilde{x}^{h_n}$$

- In that case, all other quantities will be covariant

$$S[h(x(\bar{x}, \tilde{x})), x(\bar{x}, \tilde{x})] = S[g(\bar{x}) D \dots DR, \tilde{x}]$$

- Special Coordinate Choice where non-linear terms are absent
- contact terms ↑

$$\Gamma^i_{(h_1 \dots h_n)}(\bar{x}) = 0$$

$$X^i(t) = Y^i \quad \Leftrightarrow \quad X^i(t) = Y^i \text{ is a solution}$$

to the geodesic equation; the field equation of the action.

Alvarez G.
Freedman
Mukhi

- Matrices

- The action we seek to solve

$$S \sim \int d\tau G_{ij}(x) s_\alpha \dot{x}^{i\alpha} \delta_{\beta\gamma} \dot{x}^{j\gamma}$$

is a special case of the dN^2 -NLQM

$$S \sim \int d\tau G_{i\alpha\beta,j\gamma\delta}(x) \dot{x}^{i\alpha} \dot{x}^{j\gamma}$$

if we view the triple $\{i\alpha\} \sim \mathbb{I}$. Note manifest diffeomorphism invariance.

- Matrix normal coordinates defined by

$$x^{i\alpha}(t) = t Y^{i\alpha}$$

is a solution to the field equation

- This fixes regular plus "new" diff's

$$S X \sim [X, X]$$

←
will come back to
these later

- Action will contain dN^2 -dim covariant quantities

$$S = S[G_{ij}, D_{k_1} \dots D_{k_N} R, \tilde{x}^\alpha]$$

which are functionals of d -dim covariant quantities g_{ij} & $D_{k_1} \dots D_{k_N} R$!!

Normal Coordinates & Diffeomorphisms

- Every action appears DIFF invariant ?!

- as the action, for any ordering

$$S[g_{ij}(x), D_k, \dots D_{kn} R(x), \tilde{x}]$$

only depends on covariant quantities

- Normal coordinates are based on a special point x ; diff invariance means independence of the base point x

Transformation to new normal coordinates must leave action S invariant !!

- diff translates in the symmetry

$$\begin{aligned} S S = 0 \quad ; \quad S x = \varepsilon \\ S D_i \dots D_R = \varepsilon^i D_i D_j \dots D_R \end{aligned}$$

$$S \tilde{x} = \varepsilon - \Gamma^{(n)}(\tilde{x}) \varepsilon$$

↑ solution to geodesic equation = field equation of S !!

- imposes that the ~~action~~ only depends on $X = \varepsilon + \tilde{x}$

Shift Symmetry in BG field formalism

- BG - field formalism in YM theory

- BG - Quantum Split

$$\delta(A_\mu + Q_\mu) = D_\mu(A + Q) \Lambda$$

$$\Rightarrow \begin{aligned} \delta A_\mu &= D_\mu(A) \Lambda \\ \delta Q_\mu &= [Q_\mu, \Lambda] \end{aligned}$$

- Shift Identity / Symmetry

$$\delta A_\mu = \epsilon_\mu ; \quad \delta Q_\mu = -\epsilon_\mu$$

- (Covariant) BG - field formalism in NLQH

- NONLINEAR BG - Quantum Split

$$\delta(x + \xi - \dots) = \epsilon(x + \xi - \dots)$$

$$\Rightarrow \begin{aligned} \delta x^\mu &= \epsilon^\mu(x) \\ \delta \xi^\mu &= -\epsilon^\nu \partial^\mu \xi^\nu + \xi^\nu \partial^\mu \epsilon_\nu \end{aligned}$$

- NONLINEAR Shift symmetry
(combined w change to new RNC)

$$\begin{aligned} \delta(\overset{\circ}{x} + \overset{\circ}{\xi}) &= \overset{\circ}{x} + \overset{\circ}{\chi} - "R^{(n)}" \overset{\circ}{\chi} \\ \Rightarrow \delta \xi &= \epsilon + \chi + \epsilon \nabla^a R \chi^{a+2} \end{aligned}$$

An Algorithm for Diffs

- Diffs as maps $\text{Normal Coord}_1 \leftrightarrow \text{Normal Coord}_2$ have advantage, that invariance can be imposed algorithmically.

- Write action S with all possible terms

- Impose Normal Coord₁ by requiring

$$X(\tau) = \tau Y$$

is a solution to field eq \Rightarrow constraints₁

- Change to Normal Coord₂ around ε by solving field eq order by order; substitute in action S and require that

$$S_{NC_2}[g, D..DR, \tilde{X}, \varepsilon] = S_{NC_1}[g, \varepsilon^i D_i D .. R, \tilde{X}]$$

\Rightarrow constraints₂

- Solve system of constraints 1 and 2

Normal coordinates & Matrix Geometry

- Expand the action (dN^2 -sigma model)

$$S = G_{IJ} \dot{X}^I \dot{X}^J \equiv G_{i\alpha\beta j\beta} \dot{X}^{i\alpha} \dot{X}^{j\beta}$$

in normal coordinates

- dN^2 Curvature tensors R_{IJKL} ($g, R_{ijk\ell}$) are functionals of d -curvature tensors.
- These functionals must obey the usual props.

- Impose on $R_{EJKL}, \nabla_I R_{JKLM}$, etc

a) $R_{IJKL} = -R_{JIKL} = R_{KLLIJ}$

b) $R_{I[EKL]} = 0$

c) $\nabla_E R_{JIKL} = 0$

d) $[\nabla_I, \nabla_J] R_{KLMN} = R_{IJK}{}^T R_{TLMN} + \dots$
etc.

e) $U(N)$ indices contracted in a single trace

f) Basept invariance

$$S^{\alpha\beta} \nabla_i \epsilon^\beta = \nabla_i$$

g) To first order, symmetrized result

h) Correct $U(1)$ limit

Solution

- Constraint e) implies that

$$R_{IJKL} = R_{ijkl} \Delta_{\alpha\beta\gamma\delta} + \text{orderings.}$$

$$\Delta_{\alpha\beta\gamma\delta} = S_{\alpha_1\beta_2} S_{\beta_2\gamma_1} S_{\gamma_1\delta_1} S_{\delta_1\alpha_1}$$

- At order 4, R_{IJKL} , and 5, $\nabla_I R_{JKLM}$ symmetrized result. Order 6 requires new structures due to $\{\nabla_I, \nabla_J\} R_{KLMN}$ condition.

- Answer : 120 possible terms

\downarrow
32-dim space of solutions

$$\begin{aligned} & \text{Tr}(X^n X^m X^i X^j X^k X^\ell) T_{nmiklj}^1 \\ & + \text{Tr}(X^n X^m X^i X^k X^j X^\ell) T_{nmiklj}^2 \\ & + \text{Tr}(X^n X^i X^k X^m X^\ell X^j) T_{nmiklj}^3 \end{aligned}$$

$$T_{nmiklj}^1 = \left(-\frac{7}{120} - 2\beta \right) R_{niklp} R_{nij}{}^P + 23 \text{ terms}$$

$$T_{nmiklj}^2 = \frac{1}{180} R_{njklp} R_{nilp} + 31 \text{ terms}$$

$$T_{nmiklj}^3 = \left(-\frac{47}{120} - \frac{\alpha}{5} - \frac{6\beta}{5} \right) R_{niklp} R_{njl}{}^P + 15 \text{ terms}$$

- No obvious structure emerges

Properties of the Solution

- There are new vertices cp. with $U(1)$

- $U(1)$ only $(R \dot{x})(R \dot{x})$
- $U(N)$ e.g. from T^2 : $R_{mjk} \dot{X}^j \dot{X}^k$
- appears to hold for all values of the 32 - parameters.

- The construction of the solution obscures that some of the 32 parameters will be fixed at higher order

- e.g. $\Delta S \sim \text{Tr}(\text{Asym}(\dot{X}^j X^k X^\ell) \text{ASym}(\dot{X}^m X^n X^p))$
 $\text{Right } R^{\text{unp}}$
 is left unfixed at this order.
- Unlikely all of them will be fixed at higher order
 - Bosonic string & superstring are different reps of Matrix DIFF, expect more.

The Potential, fermions, other contributions

- Need Potential for remaining two constraints of D-Geometry.

- Introduce vielbeins

$$G_{IJ} = E^A_I \cdot E^B_J \epsilon \quad E^A_I \equiv E_{i\alpha}^A$$

[U(N)-beins $G_{i\alpha j\beta} = E_{i\alpha}^a(x) E_{j\beta}^b(x)$
compatible with stringtree]

- Diff $\rightarrow SO(dN^2)$ transformation of $E_{i\alpha} X^i$
i.e. $\text{Tr } E_i^A \dot{X}^i$ transforms nicely
- Note that $[X, \dots]$ acts as d/dx
implies that $\text{Tr}([E_i^A, X^i] V)$ transforms nicely
- Some Guesswork leads to the potential

$$V = \frac{1}{2} \text{Tr} [X^i, X^j]^2 \rightarrow$$

$$= \frac{1}{4} \text{Tr} [E_i^A, X^i] [E_j^B, X^j] [E_k^C, X^k] [E_l^D, X^l]$$

- Also yields correct linearized answer

Spectrum of Quadratic Fluctuations

- Remaining constraints of D-Geometry

- Quadratic fluctuations λ have masses $m_\lambda \sim d(x_i, x_j)$
- Classical Moduli space is M^N/S_N

- Quadratic fluctuations

- diff invariance + normal coordinates imply that we only need to check

$$V|_{\lambda^2} \sim d(0, \lambda) = g_{ij}(0) \lambda^i \lambda^j$$

- CHECKS OUT !!

- Classical Moduli space M^N/S_N also follows.

Fermions and Susy

- Need Vielbeins for susy / fermions

- Appearance of vielbeins in potential is encouraging

- Susy constraints ?!

- Susy on the worldvolume should follow from kappa symmetry

- For kappa symmetry

$$\delta S^{\text{kin}} = - \delta S^{WZ}$$

need WZ - term.

- Do additional constraints arise?
for non-abelian kappa-symmetry

only closes on-shell \rightarrow

Gravitational Myers Effect I

- The Myers effect

Myers

- In the presence of RR 4-form flux

$$V(X) = -\frac{1}{4} \text{Tr} [X^i X^j]^2 - F_{ijkl} \text{Tr} X^0 X^i X^j X^k$$

- Two solutions

$$\frac{\partial V}{\partial X} = 0 \quad \left\{ \begin{array}{l} X^i = \text{diag } x_\lambda^i \\ [X^i, X^k] = i F_{ikj} X^j \end{array} \right.$$

↑ least energetic

- The non-trivial solution corresponds to a polarized D2-brane.

- Signal for Myers effect is the presence of a tachyonic mode in the spectrum of quadratic fluctuations around the trivial solution.

Jatkar et. al.

Gravitational Myers Effect II

- Question: Is there a Gravitational Myers effect?

- Is there a non-trivial critical point for the action

$$S(X) = \frac{1}{2} \text{Tr} E_i^A \dot{X}^i \text{Tr} E_j^A \dot{X}^j - \frac{1}{4} \text{Tr} [E, X]^4$$

- Highly nonlinear
- Difficult to find solutions

Sahakian

- Signal of Gravitational Myers effect: spectrum of quadratic fluctuations

i CONFLICT?

- D-Geometry: off-diagonal fluctuations have $m^2 \simeq d(x, y)^2 \geq 0$

Gravitational Myers effect III

- "Trivial" Solution is N freely falling non-interacting particles.

- $X^{bg} = \text{diag}(x_\lambda^i)$

with $\ddot{x}_\lambda^i + \Gamma_{jk}^i \dot{x}_\lambda^j \dot{x}_\lambda^k = 0$

for each entry x_λ^i .

- In D-Geometry, ultra-trivial background

$$\dot{x}_\lambda^i = 0$$

- Myers effect possible iff $\dot{x}_\lambda^i \neq 0$
Connection w. Giant Graviton? \rightarrow

- Quadratic fluctuations ?!

- Single Particle;

$$SS^{kin} = S x^i M_{ij} S x^j$$

$$M_{ij} = R i m n j \dot{x}^m \dot{x}^n + \nabla_\tau \nabla_\tau$$

- M_{ij} is the kernel of the geodesic deviation operator;
measures tidal forces!

Gravitational Myers effect IV

- Spectrum of Quadratic off-diagonal fluctuations
(around N -freely falling particles)

$$\delta^{(2)} S = \delta^{(2)} S^{\text{kin}} + S^{(2)} S^{\text{pot}}$$

$$\Rightarrow \delta^{(2)} S^{\text{pot}} = -\frac{1}{4} [x^i, y^j] [x^i, y^j]$$

$$\delta^{(2)} S^{\text{kin}} = \text{Tr } y^i M_{ij} y^j$$

$$M_{ij} = R_{imnj} \dot{x}^m \dot{x}^n + \nabla_i \nabla_j g_{ij}$$

- Myers effect occurs when
 - tidal forces \leftarrow kinetic term
 - balance internal forces \leftarrow potential term
- Does this happen? **Yes!**

When ambient space is negatively curved locally

and if $g_s^{2/3} \ll \frac{\omega^2 \ell_s^2}{L^2}$

Non-commutative Geometry

- Standard non-comm geometry

- Open strings with $B_{NS} \neq 0$

$$f \cdot g \rightarrow f * g = e^{i B \partial_x \partial_y} f(x) g(y) \Big|_{y=x}$$

- Close relations

Liu Michelso

Ozaka Ooguri

- Amplitude calculations both exhibit "Wilson lines"; linear action can be written as

$$S = \int d\lambda h_{ij}(k) \text{Tr}(e^{i\lambda k X^i} e^{i(1-\lambda)k X^j})$$

- Deformation quantization; differs preserving B_{NS}
 \Rightarrow non-comm gauge transformations

- 1-1 Map $\mathcal{F} = B + F \leftrightarrow [x, x]$

$$x^i x^j + x^j x^i = 2x^i x^j$$

$$[x^i, x^j] = B^{ij}$$

$$[x^k, [x^i, x^j]] = B^{ki} \partial_k B^{ij}$$

Is there a true Seiberg-Witten like map?

Outlook and Conclusions

- Have succeeded in finding a matrix-diffeomorphism invariant actions
 - Constructed "Matrix-Geometry"
 - Presented a solution to order 6

- Have glimpsed at the intricate geometrical structure
 - ... obvious patterns still lacking
 - Connection with non-commutative geometry

- Open questions and further directions
 - WZ terms; kappa & supersymmetry
 - Explicit Computation of Myers effect
 - Applications; Schwarzschild
 - Other Closed String backgrounds
 - Fundamental Symmetry structure
→ Matrix theory?
 - Non-Commutative YM? Ramond